

On Inverse Wave Problems – Part 2: Applications

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Wave
phenomena

Outline

Seismic Tomography

Inverse electromagnetic scattering

Summary

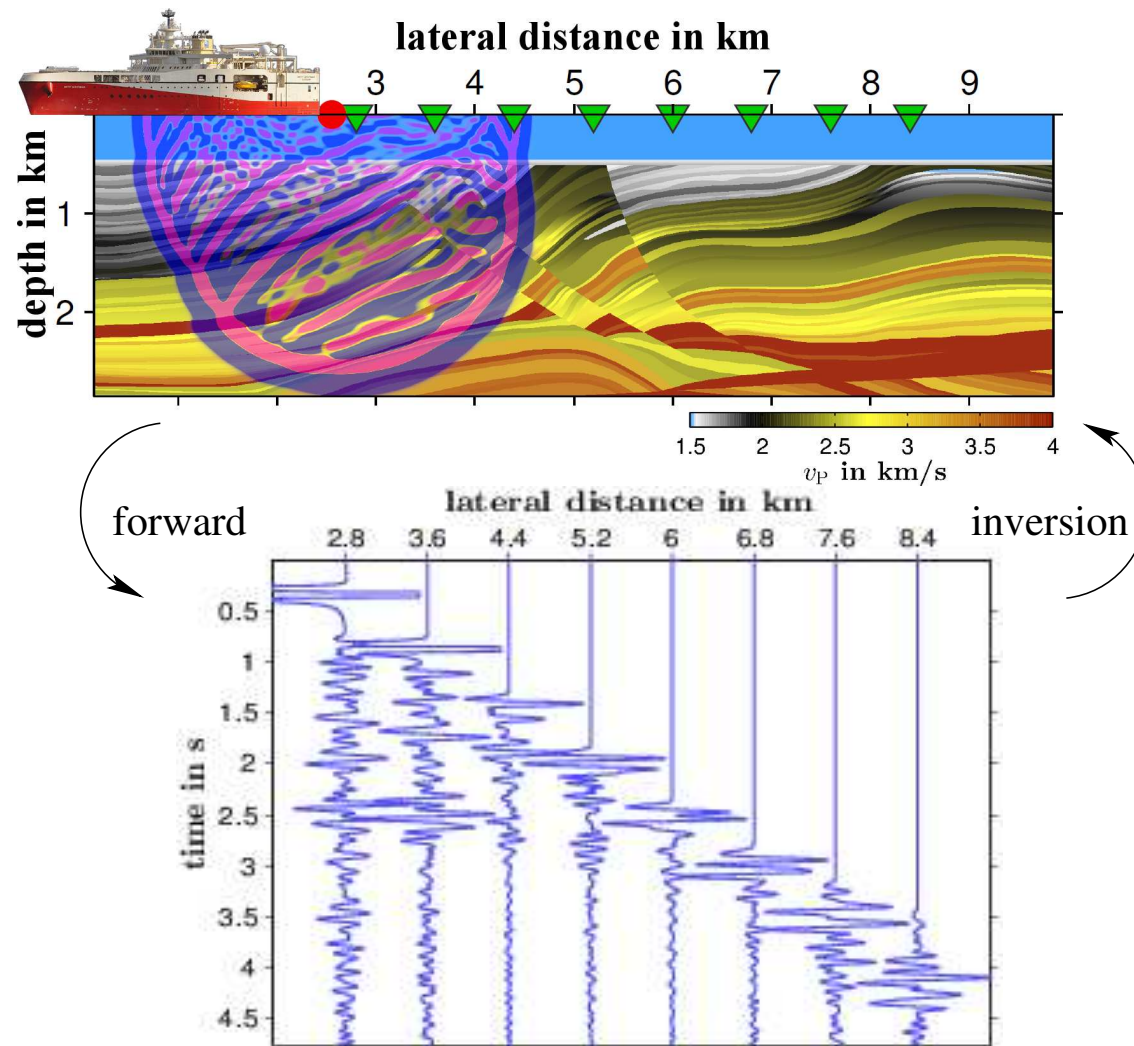
Seismic Tomog-
▷ raphy

Inverse electromag-
netic scattering

Summary

Seismic Tomography

The setting



Symes, *The seismic reflection inverse problem*, Inverse Problems 25, 123008 (2009)

The direct problem: elastic wave equation

$D \subset \mathbb{R}^3$ bounded Lipschitz domain (or an exterior of such a domain).

$\boldsymbol{\sigma}: [0, \infty) \times D \rightarrow \mathbb{R}_{\text{sym}}^{3 \times 3}$ stress tensor, $\mathbf{v}: [0, \infty) \times D \rightarrow \mathbb{R}^3$ velocity field

$$\begin{aligned} \partial_t \boldsymbol{\sigma}(t, x) &= C(\mu(x), \lambda(x)) \boldsymbol{\varepsilon}(\mathbf{v}(t, x)) && \text{in } [0, \infty) \times D, \\ \varrho(x) \partial_t \mathbf{v}(t, x) &= \operatorname{div}_x \boldsymbol{\sigma}(t, x) + \mathbf{f}(t, x) && \text{in } [0, \infty) \times D, \end{aligned}$$

where $\varrho: D \rightarrow \mathbb{R}$ mass density, $\mathbf{f}: [0, \infty) \times D \rightarrow \mathbb{R}^3$ volume force,

$$C(m, \ell) \boldsymbol{\varepsilon} = 2m \boldsymbol{\varepsilon} + \ell \operatorname{trace}(\boldsymbol{\varepsilon}) \mathbf{I}, \quad \boldsymbol{\varepsilon} \in \mathbb{R}_{\text{sym}}^{3 \times 3}, \quad m, \ell \in \mathbb{R} \quad \text{Hook's law}$$

$\mu(x), \lambda(x)$ Lamé parameters

$$\boldsymbol{\varepsilon}(\mathbf{v}) := \frac{1}{2} [(\nabla_x \mathbf{v})^\top + \nabla_x \mathbf{v}] \quad (\text{linearized}) \text{ strain}$$

► Initial and boundary conditions will be specified below.

Elastic wave equation (continued)

$$C: \mathcal{D}(C) \subset \mathbb{R}^2 \rightarrow \text{Aut}(\mathbb{R}_{\text{sym}}^{3 \times 3})$$

$$\mathcal{D}(C) = \{(m, \ell)^\top \in \mathbb{R}^2 : c^{-1} \leq 2m + 3\ell \leq c, \ c^{-1} \leq m \leq c\}$$

$$\tilde{C}(m, \ell) := C(m, \ell)^{-1} = C\left(\frac{1}{4m}, -\frac{\ell}{2m(3\ell + 2m)}\right)$$

$$\partial_t \boldsymbol{\sigma}(t, x) = C(\mu(x), \lambda(x)) \boldsymbol{\varepsilon}(\mathbf{v}(t, x))$$

$$\Longleftrightarrow \quad \tilde{C}(\mu(x), \lambda(x)) \partial_t \boldsymbol{\sigma}(t, x) = \boldsymbol{\varepsilon}(\mathbf{v}(t, x))$$

Wave equation as abstract evolution equation

- ▶ $\mathcal{P} := \{(\mu, \lambda, \varrho)^\top \in L^\infty(D)^3 : c^{-1} \leq \varrho, \mu \leq c, c^{-1} \leq 2\mu + 3\lambda \leq c \text{ a.e.}\}$
- ▶ $X = L^2(D, \mathbb{R}_{\text{sym}}^{3 \times 3}) \times L^2(D, \mathbb{R}^3)$ with inner product

$$((\boldsymbol{\sigma}, \mathbf{v})^\top, (\boldsymbol{\psi}, \mathbf{w})^\top)_X := \int_D (\boldsymbol{\sigma} : \boldsymbol{\psi} + \mathbf{v} \cdot \mathbf{w}) \, dx$$

For fixed $(\mu, \lambda, \varrho)^\top \in \mathcal{P}$ we define $B \in \mathcal{L}(X)$ by

$$B \begin{pmatrix} \boldsymbol{\sigma} \\ \mathbf{v} \end{pmatrix} := \begin{pmatrix} \tilde{C}(\mu, \lambda) & \mathbf{0} \\ \mathbf{0} & \varrho I \end{pmatrix} \begin{pmatrix} \boldsymbol{\sigma} \\ \mathbf{v} \end{pmatrix}$$

which is self-adjoint and uniformly positive definite.

Wave equation as abstract evolution equation (cont'd)

Now, the elastic wave equation may be written as

$$B \partial_t \begin{pmatrix} \boldsymbol{\sigma} \\ \mathbf{v} \end{pmatrix} + A \begin{pmatrix} \boldsymbol{\sigma} \\ \mathbf{v} \end{pmatrix} = \begin{pmatrix} \mathbf{0} \\ \mathbf{f} \end{pmatrix}, \quad \begin{pmatrix} \boldsymbol{\sigma}(0, \cdot) \\ \mathbf{v}(0, \cdot) \end{pmatrix} = \begin{pmatrix} \boldsymbol{\sigma}_0 \\ \mathbf{v}_0 \end{pmatrix},$$

with $A: \mathcal{D}(A) \subset X \rightarrow X$,

$$A := - \begin{pmatrix} 0 & \boldsymbol{\varepsilon} \\ \operatorname{div}_x & 0 \end{pmatrix},$$

where

$$\mathcal{D}(A) = \left\{ (\boldsymbol{\sigma}, \mathbf{v})^\top \in H(\operatorname{div}, D, \mathbb{R}_{\text{sym}}^{3 \times 3}) \times H_{\partial D_D}^1(D, \mathbb{R}^3) : \boldsymbol{\sigma} \mathbf{n} = \mathbf{0} \text{ on } \partial D_N \right\},$$

$$\partial D = \partial D_D \dot{\cup} \partial D_N, \quad \operatorname{vol}_2(\partial D_D) > 0.$$

Lemma A is maximal monotone ($-A$ dissipative and $R(I + A) = X$).

Existence, uniqueness, regularity

- mild/weak solution exists in $\mathcal{C}([0, \infty), X)$ for

$$\mathbf{f} \in L^1((0, \infty), L^2(D, \mathbb{R}^3)) \quad \text{and} \quad (\boldsymbol{\sigma}_0, \mathbf{v}_0)^\top \in X.$$

- classical solution exists in $\mathcal{C}([0, \infty), \mathcal{D}(A)) \cap \mathcal{C}^1([0, \infty), X)$ for

$$\mathbf{f} \in W^{1,1}((0, \infty), L^2(D, \mathbb{R}^3)) \quad \text{and} \quad (\boldsymbol{\sigma}_0, \mathbf{v}_0)^\top \in \mathcal{D}(A).$$

- classical solution exists in $\mathcal{C}^1([0, \infty), \mathcal{D}(A)) \cap \mathcal{C}^2([0, \infty), X)$ for

$$\mathbf{f} \in W^{2,1}((0, \infty), L^2(D, \mathbb{R}^3)), \quad (\boldsymbol{\sigma}_0, \mathbf{v}_0)^\top \in \mathcal{D}(A),$$

$$\varrho^{-1} [\operatorname{div} \boldsymbol{\sigma}_0 + \mathbf{f}(0)] \in H_{\partial D_D}^1(D, \mathbb{R}^3), \quad C(\mu, \lambda) \boldsymbol{\varepsilon}(\mathbf{v}_0) \in H(\operatorname{div}, D, \mathbb{R}_{\operatorname{sym}}^{3 \times 3}),$$

$$C(\mu, \lambda) \boldsymbol{\varepsilon}(\mathbf{v}_0) \mathbf{n} = \mathbf{0} \text{ on } \partial D_N.$$

The inverse problem of seismic imaging

Let $(\sigma_0, \mathbf{v}_0)^\top \in \mathcal{D}(A)$ and $\mathbf{f} \in W^{1,1}([0, T], L^2(D, \mathbb{R}^3))$ for $T > 0$.

Then, the parameter-to-solution map

$$\Phi: \mathcal{P} \subset L^\infty(D)^3 \rightarrow \mathcal{C}([0, T], X), \quad (\mu, \lambda, \varrho)^\top \mapsto (\sigma, \mathbf{v})^\top$$

is well defined.

Let $R: \mathcal{C}([0, T], X) \rightarrow \mathbb{R}^N$ be a (continuous) measurement operator.

Given $w \in \mathbb{R}^N$ find $(\mu, \lambda, \varrho)^\top \in \mathcal{P}$ such that

$$R\Phi(\mu, \lambda, \varrho) = w.$$

Solving above problem is called **full waveform inversion** in seismic imaging.

Full waveform inversion is locally ill-posed

Theorem The equation

$$\Phi(\mu, \lambda, \varrho) = (\boldsymbol{\sigma}, \mathbf{v})^\top$$

is locally ill-posed at any interior point of \mathcal{P} .

Proof: We factorize

$$\Phi = F \circ V$$

where

$$F: \mathcal{B} \subset \mathcal{L}(X) \rightarrow \mathcal{C}([0, T], X), \quad B \mapsto (\boldsymbol{\sigma}, \mathbf{v})^\top,$$

and

$$V: \mathcal{P} \subset L^\infty(D)^3 \rightarrow \mathcal{B}, \quad (\mu, \lambda, \varrho)^\top \mapsto \begin{pmatrix} \tilde{C}(\mu, \lambda) & 0 \\ 0 & \varrho I \end{pmatrix}.$$

Note that F is the mapping considered in the abstract theory.

Full waveform inversion is locally ill-posed (cont'd)

Define sequences

$$\mu_k := \mu + r_1 e_k, \quad \lambda_k := \lambda + r_2 e_k, \quad \varrho_k := \varrho + r_3 e_k$$

where $r_i \in [0, r]$, $r > 0$ sufficiently small, $r_1 + r_2 + r_3 > 0$, and

$$e_k := \chi_{B_{1/k}(\xi)} \quad \text{for one fixed } \xi \in D.$$

We have that

$$\{(\mu_k, \lambda_k, \varrho_k)\}_k \in B_r(\mu, \lambda, \varrho) \quad \text{but} \quad (\mu_k, \lambda_k, \varrho_k) \not\rightarrow (\mu, \lambda, \varrho).$$

It remains to show

$$\Phi(\mu_k, \lambda_k, \varrho_k) \rightarrow \Phi(\mu, \lambda, \varrho).$$

Full waveform inversion is locally ill-posed (cont'd)

Define $E_k \in \mathcal{L}(X)$ by

$$E_k := V(\mu_k, \lambda_k, \varrho_k) - V(\mu, \lambda, \varrho) = \begin{pmatrix} \tilde{C}(\mu_k, \lambda_k) - \tilde{C}(\mu, \lambda) & 0 \\ 0 & r_3 e_k I \end{pmatrix}$$

and show that

- ▶ E_k is monotone, symmetric, bounded,
- ▶ $\lim_{k \rightarrow \infty} \|E_k(\begin{smallmatrix} \sigma \\ \mathbf{v} \end{smallmatrix})\|_X = 0$ for all $(\sigma, \mathbf{v})^\top \in X$, and
- ▶ $\hat{r} \lesssim \|E_k\|_{\mathcal{L}(X)} \lesssim r$ for all k where $0 < \hat{r} < r$.

As

$$\Phi(\mu_k, \lambda_k, \varrho_k) = F(V(\mu, \lambda, \varrho) + E_k) \rightarrow F(V(\mu, \lambda, \varrho)) = \Phi(\mu, \lambda, \varrho)$$

the claimed local ill-posedness follows. ✓

Fréchet derivative of the forward map

Theorem The parameter-to-solution map

$$\Phi: \mathcal{P} \subset L^\infty(D)^3 \rightarrow \mathcal{C}([0, T], X)$$

is Fréchet differentiable at $(\mu, \lambda, \varrho)^\top$. In fact,

$$\Phi'(\mu, \lambda, \varrho) \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = \begin{pmatrix} \overline{\sigma} \\ \overline{\mathbf{v}} \end{pmatrix}$$

where $(\overline{\sigma}, \overline{\mathbf{v}})^\top \in \mathcal{C}([0, T], X)$ is the mild solution of

$$\partial_t \overline{\sigma}(t, x) = C(\mu(x), \lambda(x)) \varepsilon(\overline{\mathbf{v}}(t, x)) + C(h_1(x), h_2(x)) \varepsilon(\mathbf{v}(t, x)),$$

$$\varrho(x) \partial_t \overline{\mathbf{v}}(t, x) = \operatorname{div} \overline{\sigma}(t, x) - h_3(x) \partial_t \mathbf{v}(t, x),$$

in $[0, T] \times D$ with $\overline{\sigma}(0) = \mathbf{0}$, $\overline{\mathbf{v}}(0) = \mathbf{0}$. Here, $\mathbf{v} = \Phi(\mu, \lambda, \varrho)_2$.

Fréchet derivative of the forward map (continued)

Proof: As $\Phi = F \circ V$ we have that

$$\Phi'(\mu, \lambda, \varrho) = F'(V(\mu, \lambda, \varrho))V'(\mu, \lambda, \varrho).$$

The assertion follows from

$$\begin{aligned} V'(\mu, \lambda, \varrho) \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} &= \begin{pmatrix} \tilde{C}'(\mu, \lambda) & 0 \\ 0 & I \end{pmatrix} \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} \\ &= \begin{pmatrix} -\tilde{C}(\mu, \lambda)C(h_1, h_2)\tilde{C}(\mu, \lambda) & 0 \\ 0 & h_3 I \end{pmatrix} \end{aligned}$$

and the abstract result applied to F . ✓

Second order wave equation

$$\rho(x) \partial_{tt} \mathbf{v}(t, x) = \operatorname{div} [C(\mu(x), \lambda(x)) \boldsymbol{\varepsilon}(\mathbf{v}(t, x))] + \mathbf{g}(t, x)$$

with $\mathbf{v}(0, \cdot) = \mathbf{v}_0$, $\partial_t \mathbf{v}(0, \cdot) = \mathbf{v}_1$ in D , and

$$\mathbf{v} = \mathbf{0} \text{ on } [0, T] \times \partial D_D, \quad C(\mu, \lambda) \boldsymbol{\varepsilon}(\mathbf{v}) \mathbf{n} = \mathbf{0} \text{ on } [0, T] \times \partial D_N.$$

Set

$$\boldsymbol{\sigma}(t, x) := C(\mu(x), \lambda(x)) \int_0^t \boldsymbol{\varepsilon}(\mathbf{v}(s, x)) \, ds.$$

Then, $(\boldsymbol{\sigma}, \mathbf{v})$ solves

$$\begin{aligned} \partial_t \boldsymbol{\sigma}(t, x) &= C(\mu(x), \lambda(x)) \boldsymbol{\varepsilon}(\mathbf{v}(t, x)), \\ \rho(x) \partial_t \mathbf{v}(t, x) &= \operatorname{div} \boldsymbol{\sigma}(t, x) + \int_0^t \mathbf{g}(s, x) \, ds + \rho(x) \mathbf{v}_1(x) \end{aligned}$$

with $\mathbf{v}(0, \cdot) = \mathbf{v}_0$, $\boldsymbol{\sigma}(0, \cdot) = \mathbf{0}$ in D , and

$$\mathbf{v} = \mathbf{0} \text{ on } [0, T] \times \partial D_D, \quad \boldsymbol{\sigma} \mathbf{n} = \mathbf{0} \text{ on } [0, T] \times \partial D_N.$$

Second order wave equation (continued)

Conclusion

- ▶ Our results carry over to the second order wave equation.
- ▶ Thus, we regain and extend results of
LECHLEITER/SLASCHE 2015 and BOEHM/ULBRICH 2015
on the Fréchet differentiability of the parameter-to-solution map.

Seismic Tomography

Inverse elec-
tromagnetic
▷ scattering

Summary

Inverse electromagnetic scattering

The Maxwell system

$\mathbf{E} = \mathbf{E}(t, \mathbf{x})$ and $\mathbf{H} = \mathbf{H}(t, \mathbf{x})$ electric and magnetic fields, resp.

$$\underbrace{\begin{pmatrix} \varepsilon I & 0 \\ 0 & \mu I \end{pmatrix}}_{= B} \partial_t \begin{pmatrix} \mathbf{E} \\ \mathbf{H} \end{pmatrix} = - \underbrace{\begin{pmatrix} \sigma I & -\text{curl}_x \\ \text{curl}_x & 0 \end{pmatrix}}_{= A} \begin{pmatrix} \mathbf{E} \\ \mathbf{H} \end{pmatrix} + \underbrace{\begin{pmatrix} -\mathbf{J}_e \\ \mathbf{J}_m \end{pmatrix}}_{= f} \quad \text{in } (0, T) \times D$$

with bc: $\mathbf{n} \times \mathbf{E} = 0$ on $(0, T) \times \partial D$

ic: $\mathbf{E}(0, \cdot) = \mathbf{e}_0, \mathbf{H}(0, \cdot) = \mathbf{h}_0$

where $\mathbf{J}_{e/m} = \mathbf{J}_{e/m}(t, x)$ current/magnetic density

$\varepsilon = \varepsilon(x)$ permittivity

$\mu = \mu(x)$ permeability

$\sigma = \sigma(x)$ conductivity

Abstract settings

- ▶ $\mathcal{P} := \{(\varepsilon, \mu)^\top \in L^\infty(D)^2 : c^{-1} \leq \varepsilon, \mu \leq c \text{ a.e.}\}$
- ▶ $X = L^2(D, \mathbb{R}^3) \times L^2(D, \mathbb{R}^3)$

If $(\varepsilon, \mu)^\top \in \mathcal{P}$ then $B \in \mathcal{L}(X)$ is self-adjoint and uniformly pos. definite.

- ▶ $\sigma \in L^\infty(D), \sigma \geq 0$
- ▶ $\mathcal{D}(A) = H_0(\text{curl}, D) \times H(\text{curl}, D)$

Lemma $A: \mathcal{D}(A) \subset X \rightarrow X$ is maximal monotone.

Electromagnetic scattering operator

Let $(\mathbf{e}_0, \mathbf{h}_0)^\top \in \mathcal{D}(A)$ and $(\mathbf{J}_e, \mathbf{J}_m)^\top \in W^{1,1}([0, T], X)$ for $T > 0$.

Then, the parameter-to-solution map is well defined:

$$\Phi: \mathcal{P} \subset L^\infty(D)^2 \rightarrow \mathcal{C}([0, T], X), \quad (\varepsilon, \mu)^\top \mapsto (\mathbf{E}, \mathbf{H})^\top.$$

We factorize again

$$\Phi = F \circ V$$

where

$$F: \mathcal{B} \subset \mathcal{L}(X) \rightarrow \mathcal{C}([0, T], X), \quad B \mapsto (\mathbf{E}, \mathbf{H})^\top,$$

and

$$V: \mathcal{P} \subset L^\infty(D)^2 \rightarrow \mathcal{B}, \quad (\varepsilon, \mu)^\top \mapsto \begin{pmatrix} \varepsilon I & 0 \\ 0 & \mu I \end{pmatrix}.$$

Conclusion: Fréchet-differentiability and local ill-posedness hold for inverse electromagnetic scattering as well.

Seismic Tomography

Inverse electromagnetic scattering

▷ Summary

Summary

Things to remember

$$Bu'(t) + Au(t) = f(t), \quad t \geq 0, \quad u(0) = u_0$$

$B \in \mathcal{L}(X)$ pos. self-adjoint; $A: \mathcal{D}(A) \subset X \rightarrow X$ maximal monotone;
 X Hilbert space

$$F: B \mapsto u$$

We have investigated the

- ▶ Fréchet-differentiability of F ,
- ▶ Local ill-posedness of $F(\cdot) = u$,

and applied our abstract findings to

- ▶ the elastic wave equation (seismic tomography),
- ▶ Maxwell's system (inverse electromagnetic scattering).