

The Born Approximation for the Wave Equation

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Outline of the talk

- (A) Introduction
- (B) The Initial Boundary Value Problem
- (C) Lipschitz-Continuity and Differentiability
- (D) Remarks on the Born-Approximation
- (E) Ill-Posedness of the Inverse Problem
- (F) Final Remarks

(A) Introduction

Born Approximation for Helmholtz equation: $u = u^i + u^s$ total field

$$\Delta u + k^2(1 + q)u = 0; \text{ that is, } \Delta u + k^2u = -k^2qu$$

$$\Delta u^s + k^2u^s = -k^2qu; \text{ that is, } u^s(x) = k^2 \int_D q(y)u(y) \Phi_k(x, y) dy$$

Lippmann-Schwinger equation:

$$u(x) = u^i(x) + k^2 \int_D q(y)u(y) \Phi_k(x, y) dy, \quad x \in D.$$

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Born series: $u_0 = u^i$, $\Delta u_{j+1} + k^2 u_{j+1} = -k^2 q u_j$, that is

$$u_{j+1}(x) = u^i(x) + k^2 \int_D q(y) u_j(y) \Phi_k(x, y) dy, \quad x \in D.$$

L^2 -convergence if $k^4 \int_D \int_D q(y)^2 \Phi_k(x, y)^2 dy dx < 1$

Introduction, cont.

(Linearized) wave equation:

$$\frac{1}{\varrho v^2} \partial_t^2 u(x, t) - \nabla_x \cdot \left(\frac{1}{\varrho} \nabla_x u(x, t) \right) = f(x, t), \quad (x, t) \in \Omega \times (0, T],$$

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Set $a = 1/(\varrho v^2)$ and $b = 1/\varrho$, thus:

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Boundary conditions:

$$u(\cdot, t)|_{\partial\Omega} = 0,$$

Initial conditions:

$$u(\cdot, 0) = u_0; \quad \partial_t u(\cdot, 0) = u_1 \text{ on } \Omega.$$

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Inverse problem studies mapping $\mathcal{F} : (a, b) \mapsto \Psi u$ (for example $\Psi u = u|_D$ for some $D \subset \Omega$).

Introduction, cont.

Usually a, b are **perturbations** of known \hat{a}, \hat{b} ; that is, $a = \hat{a} + \varepsilon \tilde{a}$ and $b = \hat{b} + \varepsilon \tilde{b}$. Formally, $u = \hat{u} + \varepsilon u' + o(\varepsilon)$ where

$$\hat{a} \partial_t^2 u' - \nabla_x \cdot (\hat{b} \nabla_x u') = -\tilde{a} \partial_t^2 \hat{u} + \nabla_x \cdot (\tilde{b} \nabla_x \hat{u}), \quad (x, t) \in \Omega \times (0, T],$$

where \hat{u} is solution corresponding to \hat{a} and \hat{b} .

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Goal of talk:

- Justify this rigorously as Fréchet derivative in proper function spaces
- Clarify why Born-series is not well defined
- Show that nonlinear inverse problem is improperly posed (in the sense of Hofmann 1997)

(B) The Initial Boundary Value Problem

Weak formulation (Green's first formula w.r.t. time and space variable):

$$\int_0^T \int_{\Omega} [b(x) \nabla_x u(x, t) \cdot \nabla_x \psi(x, t) - a(x) \partial_t u(x, t) \partial_t \psi(x, t)] dx dt$$

$$= \int_0^T \int_{\Omega} f(x, t) \psi(x, t) dx dt \quad \text{for all } \psi \in C^\infty(\overline{\Omega} \times [0, T]) \text{ with } \psi(\cdot, T) = 0.$$

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Identify $u : \Omega \times (0, T) \rightarrow \mathbb{R}$ with $u : (0, T) \rightarrow H_0^1(\Omega)$ and $\dot{u} = \partial_t u$. Then:

$$\int_0^T (b \nabla u(t), \nabla \psi(t))_{L^2} - (a \dot{u}(t), \dot{\psi}(t))_{L^2} dt = \int_0^T (f(t), \psi(t))_{L^2} dt$$

for all $\psi \in C^\infty([0, T], C^\infty(\overline{\Omega}))$ with $\psi(0) = \psi(T) = 0$.

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for all $\psi \in C^\infty([0, T], C^\infty(\overline{\Omega}))$ with $\psi(0) = \psi(T) = 0$. **Solution space:**

$$X = C^1([0, T], L^2(\Omega)) \cap C([0, T], H_0^1(\Omega))$$

with norm $\|u\|_X := \left(\max_{0 \leq t \leq T} \|u(t)\|_{H^1}^2 + \max_{0 \leq t \leq T} \|\dot{u}(t)\|_{L^2}^2 \right)^{1/2}$.

Then also test functions $\psi \in X$ with $\psi(0) = \psi(T) = 0$. In addition, initial conditions $u(0) = u_0$ and $\dot{u}(0) = u_1$.

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Assumptions: $a, b \in L^\infty(\Omega)$ with $\gamma \leq a(x), b(x) \leq \gamma^{-1}$ a.e. on Ω , $f \in L^2((0, T) \times \Omega) = L^2((0, T), L^2(\Omega))$, $u_0 \in H_0^1(\Omega)$, $u_1 \in L^2(\Omega)$.

The Spectral Method

Under these assumptions there exists a unique solution. Approaches:
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s.a. EVP: $-\nabla \cdot (b \nabla v_n) = \lambda_n^2 a v_n$ in Ω , $v_n = 0$ on $\partial\Omega$, that is,

$$v_n \in H_0^1(\Omega), \quad \underbrace{\int_{\Omega} b \nabla v_n \cdot \nabla \psi \, dx}_{= (v_n, \psi)_{1,b}} = \lambda_n^2 \underbrace{\int_{\Omega} a v_n \psi \, dx}_{= (v_n, \psi)_{0,a}} \quad \forall \psi \in H_0^1(\Omega).$$

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Set $V = (H_0^1(\Omega), (\cdot, \cdot)_{1,b})$. Normalize $v_n \in V$ such that $\|v_n\|_{1,b} = 1$.

Then: $\{v_n : n \in \mathbb{N}\}$ ONS in V and $\{\lambda_n v_n : n \in \mathbb{N}\}$ ONS in $L^2(\Omega, a \, dx)$.

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Also (because $\gamma b \leq 1$ and $b \geq \gamma$) with Poincaré's constant c_{Ω} :

$$\gamma \|v\|_{1,b}^2 \leq \|v\|_{H^1}^2 \leq (1 + c_{\Omega}^2) \|\nabla v\|_{L^2}^2 \leq \frac{1 + c_{\Omega}^2}{\gamma} \|v\|_{1,b}^2,$$

$$\gamma \|v\|_{0,a}^2 \leq \|v\|_{L^2}^2 \leq \frac{1}{\gamma} \|v\|_{0,a}^2.$$

The Spectral Method, cont.

Let $u_0 = \sum_n \alpha_n v_n$ in V and $u_1 = \sum_n \beta_n \lambda_n v_n$ in $L^2(\Omega, a dx)$ and

$$\frac{f(t)}{a} = \sum_n f_n(t) \lambda_n v_n \text{ in } L^2(\Omega, a dx).$$

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Define $\eta_n(t) = \int_0^t \sin(\lambda_n(t-s)) f_n(s) ds, \quad t \in [0, T], \quad n \in \mathbb{N}.$

Then $u(t) = \sum_n [\alpha_n \cos(\lambda_n t) + \beta_n \sin(\lambda_n t) + \eta_n(t)] v_n$

is the unique weak solution of $a \partial_t^2 u - \nabla \cdot (b \nabla u) = f$ in $\Omega \times (0, T)$ with $u(0) = u_0$ in Ω , $\partial_t u(0) = u_1$ in Ω , and $u = 0$ on $\partial\Omega \times (0, T)$

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$$\begin{aligned} \|u(t)\|_{1,b}^2 + \|\dot{u}(t)\|_{0,a}^2 &\leq 2 \cdot 3 \sum_n [\alpha_n^2 + \beta_n^2 + T \|f_n\|_{L^2(0,T)}^2] \\ &\leq 6 [\|u_0\|_{1,b}^2 + \|u_1\|_{0,a}^2 + (T/\gamma) \|f\|_{L^2(\Omega \times (0,T))}^2]. \end{aligned}$$

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Furthermore, $a \ddot{u} \in L^2((0, T), H^{-1}(\Omega))$ and

$$(b \nabla u(t), \nabla \psi)_{L^2} + \langle a \ddot{u}(t), \psi \rangle = (f(t), \psi)_{L^2} \quad \text{for all } \psi \in H_0^1(\Omega), \text{ a.e.}$$

Regularity

From this approach one gets easily regularity. Recall:

$$u(t) = \sum_n [\alpha_n \cos(\lambda_n t) + \beta_n \sin(\lambda_n t) + \eta_n(t)] v_n \quad \text{with}$$

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Theorem

(a) If $\nabla \cdot (b \nabla u_0) \in L^2(\Omega)$, $u_1 \in H_0^1(\Omega)$, $f \in H^1((0, T), L^2(\Omega))$ then

$$u \in C^1([0, T], H_0^1(\Omega)) \cap C^2([0, T], L^2(\Omega)).$$

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(b) If $\frac{1}{a} [\nabla \cdot (b \nabla u_0) - f(0)] \in H_0^1(\Omega)$, $\nabla \cdot (b \nabla u_1) \in L^2(\Omega)$, $f \in H^2((0, T), L^2(\Omega))$ then

$$u \in C^2([0, T], H_0^1(\Omega)) \cap C^3([0, T], L^2(\Omega)) .$$

Example

$$\int_0^T (b \nabla u(t), \nabla \psi(t))_{L^2} - (a \dot{u}(t), \dot{\psi}(t))_{L^2} dt = \int_0^T (f(t), \psi(t))_{L^2} dt$$

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Example: $\Omega = (0, \pi) \times (0, \pi)$, $a = b = 1$. Then

$$v_n(x_1, x_2) = \frac{2}{\pi|n|} \sin(n_1 x_1) \sin(n_2 x_2), \quad n = (n_1, n_2) \in \mathbb{N}^2,$$

is ONS in $H_0^1(\Omega)$ wrt $(\nabla u, \nabla v)_{L^2}$ and $\{|n|v_n : n \in \mathbb{N}^2\}$ is ONS in $L^2(\Omega)$.

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Define $f(x, t) = \sum_{n \in \mathbb{N}^2} \rho_n |n|^2 \cos(|n|t) v_n(x)$ with $\sum_n \rho_n^2 < \infty$.

Example

$$\int_0^T (b \nabla u(t), \nabla \psi(t))_{L^2} - (a \dot{u}(t), \dot{\psi}(t))_{L^2} dt = \int_0^T (f(t), \psi(t))_{L^2} dt$$

for all $\psi \in X$ with $\psi(0) = \psi(T) = 0$.

Remark: $f \in L^2((0, T), H^{-1}(\Omega))$ not sufficient for $u \in X$!

Example: $\Omega = (0, \pi) \times (0, \pi)$, $a = b = 1$. Then

$$v_n(x_1, x_2) = \frac{2}{\pi|n|} \sin(n_1 x_1) \sin(n_2 x_2), \quad n = (n_1, n_2) \in \mathbb{N}^2,$$

is ONS in $H_0^1(\Omega)$ wrt $(\nabla u, \nabla v)_{L^2}$ and $\{|n|v_n : n \in \mathbb{N}^2\}$ is ONS in $L^2(\Omega)$.

Define $f(x, t) = \sum_{n \in \mathbb{N}^2} \rho_n |n|^2 \cos(|n|t) v_n(x)$ with $\sum_n \rho_n^2 < \infty$.

Then $f \in L^2((0, T), H^{-1}(\Omega))$ and

$$u(t) = -\frac{1}{2} \sum_{n \in \mathbb{N}^2} \rho_n |n| t \sin(|n|t) v_n \in L^2(\Omega).$$

(C) Lipschitz-Continuity and Differentiability

$$\begin{aligned}
 a_j \ddot{u}_j(t) - \nabla \cdot (b_j \nabla u_j(t)) &= f(t), \quad j = 1, 2. \quad \text{Set } u := u_1 - u_2 : \\
 a_2 \ddot{u}(t) - \nabla \cdot (b_2 \nabla u(t)) &= (a_2 - a_1) \ddot{u}_1(t) - \nabla \cdot ((b_2 - b_1) \nabla u_1(t)) \\
 &= (a_2 - a_1) \ddot{u}_1(t) - \nabla \cdot (b_2 \nabla w(t))
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where $w(t) \in H_0^1(\Omega)$ solves $\nabla \cdot (b_2 \nabla w(t)) = \nabla \cdot ((b_2 - b_1) \nabla u_1(t))$.

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Assumption: $\nabla \cdot (b_1 \nabla u_0) \in L^2(\Omega)$, $u_1 \in H_0^1(\Omega)$, $f \in H^1((0, T), L^2(\Omega))$.

Then $u_1 \in C^1([0, T], H_0^1(\Omega)) \cap C^2([0, T], L^2(\Omega))$.

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Then $u_1 \in C^1([0, T], H_0^1(\Omega)) \cap C^2([0, T], L^2(\Omega))$. Thus:

$(a_2 - a_1) \ddot{u}_1 \in L^2((0, T) \times \Omega)$ and also $w \in C^1([0, T], H_0^1(\Omega))$ and $\|w(t)\|_{1, b_2} \leq \frac{1}{\gamma} \|b_2 - b_1\|_\infty \|u_1(t)\|_{1, b_2}$. Thus:

$$\begin{aligned}
 \|u_1 - u_2\|_X &\leq \tilde{c} [\|(a_2 - a_1) \ddot{u}_1\|_{L^2((0, T) \times \Omega)} + \|w\|_{H^1((0, T), H_0^1(\Omega))}] \\
 &\leq c [\|a_2 - a_1\|_\infty + \|b_2 - b_1\|_\infty]
 \end{aligned}$$

where c depends only on T , Ω , γ , u_0 , u_1 , and f .

Theorem: Let $f \in H^2((0, T), L^2(\Omega))$. Set

$$U = \{v \in L^\infty(\Omega) : \gamma \leq v \leq \gamma^{-1} \text{ a.e. on } \Omega\}.$$

Furthermore, let $(\hat{a}, \hat{b}) \in \text{int}(U) \times \text{int}(U)$ and the initial data satisfy $\frac{1}{\hat{a}}[\nabla \cdot (\hat{b} \nabla u_0) - f(0)] \in H_0^1(\Omega)$ and $\nabla \cdot (\hat{b} \nabla u_1) \in L^2(\Omega)$.

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$$\hat{a} \partial_t^2 u' - \nabla \cdot (\hat{b} \nabla u') = -a \partial_t^2 \hat{u} + \nabla \cdot (b \nabla \hat{u}) \quad \text{in } \Omega \times (0, T],$$

and $u'(0) = \partial_t u'(0) = 0$. Here, $\hat{u} = \mathcal{F}(\hat{a}, \hat{b})$.

(D) Remarks on the Born-Approximation

Let, for simplicity, $u_0 = u_1 = 0$. Recall: $a \hat{=} \hat{a} + a$ and $b \hat{=} \hat{b} + b$ and $u \in X$ satisfies

$$(\hat{a} + a) \partial_t^2 u - \nabla_x \cdot ((\hat{b} + b) \nabla_x u) = f; \quad \text{that is,}$$

$$\hat{a} \partial_t^2 u - \nabla_x \cdot (\hat{b} \nabla_x u) = f - a \partial_t^2 u + \nabla_x \cdot (b \nabla_x u).$$

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Introduce **linear solution operator** $L : g \mapsto \hat{u}$ where $\hat{u} \in X$ solves

$$\hat{a} \partial_t^2 \hat{u} - \nabla_x \cdot (\hat{b} \nabla_x \hat{u}) = g.$$

Then u solves fixed point equation

$$u = L[f - a \partial_t^2 u + \nabla_x \cdot (b \nabla_x u)] = Lf - L[a \partial_t^2 u - \nabla_x \cdot (b \nabla_x u)].$$

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Born series is the same as fixed point iteration; that is, $u_0 = Lf = \hat{u}$ and

$$u_{k+1} = \hat{u} - L[a \partial_t^2 u_k - \nabla_x \cdot (b \nabla_x u_k)], \quad k = 0, 1, 2, \dots$$

Remarks on the Born-Approximation, cont.

Recall:

$$u_{k+1} = \hat{u} - L[a\partial_t^2 u_k - \nabla_x \cdot (b\nabla_x u_k)], \quad k = 0, 1, 2, \dots$$

First step $k = 0$:

$$u_1 = \hat{u} - L[a\partial_t^2 u_0 - \nabla_x \cdot (b\nabla_x u_0)] = \hat{u} + u';$$

that is, first Born approximation coincides with Fréchet-linearization.

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Note that L is bounded from $L^2((0, T) \times \Omega)$ into $X = C^1([0, T], L^2(\Omega)) \cap C([0, T], H_0^1(\Omega))$ but

$$a\partial_t^2 u_k - \nabla_x \cdot (b\nabla_x u_k) \notin L^2((0, T) \times \Omega) \quad \text{for } u_k \in X!$$

Therefore, Born series is not even well-defined!

(E) Ill-Posedness of the Inverse Problem

Definition (Hofmann 1997) An equation $\mathcal{F}y = u$ is called **locally ill-posed** in $y^* \in D(\mathcal{F})$ with $\mathcal{F}y^* = u$ if in any neighborhood of y^* there is a sequence $y_j \in D(\mathcal{F})$ with $\mathcal{F}(y_j) \rightarrow \mathcal{F}(y^*)$ but $y_j \not\rightarrow y^*$.

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In our case $\mathcal{F} : Y^* \rightarrow Z$ with $Y^* = L^\infty(\Omega) \times L^\infty(\Omega)$; that is, $Y = L^1(\Omega) \times L^1(\Omega)$, and $Z = L^2((0, t) \times \Omega)$.

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Proposition Let $\mathcal{F} : Y^* \rightarrow Z$ be compact and weak- $*$ -to-weak continuous. Further, let $y^* \in D(\mathcal{F})$ satisfy $\mathcal{F}y^* = u$ and assume the existence of a sequence $e_j \in Y^*$ with $\|e_j\|_{Y^*} = 1$ and $e_j \rightarrow 0$ weakly- $*$ and $y^* + re_j \in D(\mathcal{F})$ for every $r \in [0, 1]$ and $j \in \mathbb{N}$. Then the equation $\mathcal{F}y = u$ is locally ill-posed.

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Assumptions are satisfied in this case! Compactness of \mathcal{F} by Theorem of Arzela-Ascoli:

$$\begin{aligned} \|u(t_2) - u(t_1)\|_{L^2} &= \sup_{\|\psi\|_{L^2}=1} (u(t_2) - u(t_1), \psi)_{L^2} = \sup_{\|\psi\|_{L^2}=1} \int_{t_1}^{t_2} (\dot{u}(s), \psi)_{L^2} ds \\ &\leq |t_2 - t_1| \|\dot{u}\|_{C([0, T], L^2(\Omega))} \end{aligned}$$

Ill-Posedness of the Inverse Problem, cont.

Weak- $*$ -to-weak continuity by variational formulation of differential equation.

III-Posedness of the Inverse Problem, cont.

Weak-* to weak continuity by variational formulation of differential equation.

Construction of $e_j \in L^\infty(\Omega)$ with $\|e_j\|_{L^\infty} = 1$ and $e_j \rightarrow 0$ weakly-* and $y^* + re_j \in D(\mathcal{F})$:

Let $z \in \Omega$ and let $B_j = B(z, 1/j)$ be ball centered at z with radius $1/j$. Set $e_j = \chi_{B_j}$ characteristic function of B_j . Then $\|e_j\|_{L^\infty} = 1$ and $e_j \rightarrow 0$ weakly-*.

III-Posedness of the Inverse Problem, cont.

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Theorem Let the measurement operator $\Psi : L^2(\Omega) \rightarrow L^2(D)$ be linear and bounded. Then the problem to determine the parameters $a, b \in L^\infty(\Omega)$ from Ψu is ill-posed.

(F) Final Remarks

References:

- On the Linearization of Operators Related to the Full Waveform Inversion in Seismology. MMAS 2014
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Extensions

- Maxwell's equations analogously, data-to-solution operator $\mathcal{F} : (\varepsilon, \mu) \mapsto (E, H)$ not compact because $H(\text{curl}, \Omega)$ not compactly imbedded in $L^2(\Omega)$.
- Elasticity problem recently by John Schlasche (student of Armin).

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Thank you for your attention and, in particular,

thank you, Armin, for this phantastic workshop!