

Precise Prediction of Workpiece Distortion during Laser Beam Welding



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Laser Welding Process Overview

Objective

Simulation Model

Work in Progress

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Laser Welding: Deep Penetration Welding Characteristics



<u>Definition</u>: A keyhole fusion welding technique achieved with the very high power density obtained by focusing a beam of laser light to a very fine spot

Energy absorption by multiple beam reflection inside the keyhole

Keyhole held open by the vapour pressure

Laser Welding: Why Laser Welding?

Advantages	Disadvantages
Low heat input - low thermal distortion - reduced metallurgical damage e.g. grain growth	Precise beam joint alignment
High welding speed due to high beam power density - high production rates	Close fitting and clamped joints
High process flexibility - applicable to all welding position	High equipment and operating costs
 Welding thick workpiece in one pass weld penetration depth limited by available laser power (not by conductivity of the workpiece material) 	Not portable (workshop-based) due to the large size of the equipments (e.g. power supplies) and compulsarily controlled environment due to safety reasons

Laser Welding: Weld Cross Section



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Laser Welding: Cause of Distortion in Welding



Distortion Caused by Inhomogeneous Temperature Distribution



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Developing a precise simulation model for workpiece distortion prediction

Determination of relationship between weld geometry and degree of workpiece deformation

Solution:

"Coupling of fluid dynamics simulation (accurate heat source) and solid structure simulation (calculating workpiece distortion)"



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Simulation Model Coupling Principle Solid Structure Simulation Fluid Flow Simulation Alberta Implementation

Work in Progress

Coupling Principle

Stationary Heat Source:

Fluid flow simulation with given constant boudary conditions

Solid structure simulation with the temperature gradient gained from the fluid f



boundary conditions

Fluid flow simulation with current timestep boundary conditions from the solid of Dynamic Heat Source:

Solid structure simulation with the temperature gradient gained from the fluid t



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Solid Structure Simulation: Thermal Calculation

Heat Equation

C_p(T) : T₀ :

$$\frac{\partial T}{\partial t} - \nabla \cdot \left(\frac{k(T)}{\rho(T)c_p(T)} \cdot \nabla T\right) = 0 \qquad \text{on } \Omega \times (0,\tau)$$

 $T = T_{source}$ on $\Gamma_D \times (0, \tau)$

$$-(k(T) \cdot \nabla T) \cdot n = h(T) \cdot (T - T_0) \quad \text{ on } \Gamma_N \times (0, \tau)$$

$$T(x,0) = T_0 \qquad on \ \Omega$$

- T : Temperature [°C]
- $\rho(T)$: Temperature-dependent density [kg/mm³]
- k(T) : Temperature-dependent thermal conductivity [W/mm°C]
- h(T) : Temperature-dependent thermal transfer coefficient (air) [W/mm²°C]
 - Temperature-dependent specific heat [J/kg°C]
 - Room temperature [°C]

Solid Structure Simulation: Mechanical Calculation

Momentum Equation (Displacement Calculation)

 $-\nabla \cdot \sigma = 0 \quad \text{on } \Omega \times (0,\tau) \quad ; \sigma = \sigma(u,T,\epsilon^{p})$ $u = 0 \quad \text{on } \Gamma_{D} \times (0,\tau)$ $\sigma \cdot n = 0 \quad \text{on } \Gamma_{N} \times (0,\tau)$

 σ : stress [N/mm], u: displacement [mm], ϵ^{p} : plastic strain [-]

Plasticity Theory (Stress and Plastic Strain Calculation)



Isotropic strain hardening employed

Radial return mapping employed

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Fluid Flow Simulation (Research State)

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Alberta Implementation

ALBERTA Concept

Adaptive Finite Element Toolbox (simplex elements) Refinement technique: Bisectioning Error estimator type: Residual error estimator

Applied Refinement and Coarsening Strategy (Solid Struture) Strategy: Implicit (time step control) and equidistribution (element size control) strategy Error estimator: Based solely on the heat equation

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Work in Progress: Project Status

Modified solid structure simulation model from the forerunner project obtained with a simplified analytical keyhole model (calculated keyhole geometry)

Fluid flow simulation model not yet created (research stage)

Coupling not yet researched

Work in Progress: Experiment and Simulation Setup

Simulation Setup



Workpiece: 200x50x10 mm Welding Speed: 50 mm/s Laser Power: 3000 W Weld Length: 140 mm Cooling Time: 12 s Keyhole Model: Jüptner Thermal BCs:

- 3000 °C (vapour) inside keyhole
- Radiation and convection

Mechanical BCs: Supports at 3 points

Work in Progress: Simulation Results

Temperature Development



Temperature history of three different points measured on the top surface of the workpiece



Work in Progress: Simulation Results

Workpiece Deformation



Deformation of the workpiece indicated by the displacement in Z direction measured on the top surface





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Thank You for Your Attention