



On Generalized Gradient Methods for Non-differentiable Functionals

Application to Tikhonov Functionals with Sparsity Constraints

Dirk A. Lorenz – joint work with Kristian Bredies

RICAM Linz, 2007-02-27



- 1 The Problem: Sparsity Constraints
- 2 Gradient Methods
 - Classical Gradient Methods
 - Generalizations
- 3 Application to Tikhonov Functionals
 - Soft shrinkage
 - Hard shrinkage
- 4 Examples
 - Backwards heat conduction
 - Inverse integration



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What this talk is about

$$\min_{u \in H} \frac{\|Ku - f\|^2}{2} + \Phi(u)$$

- Tikhonov functionals for ill-posed problems
- Regularized optimal control problems

Φ models **prior knowledge** or a known **constraint**, e.g:

A sparsity constraint

For a given basis (ψ_k) and convex ϕ :

$$\Phi(u) = \sum_k \phi(\langle u, \psi_k \rangle),$$

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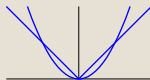
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Problems with minimization

$$\min_{u \in \ell^2} \frac{\|Ku - f\|_{\ell^2}^2}{2} + \sum_k w_k |u_k|^p$$

- Ill-posed problems:

The functional $\|Ku - f\|^2$ has no minimizer.

- $1 \leq p < 2$: The functional $\sum_k |\langle u, \psi_k \rangle|^p$ is non-smooth.

Goal of this talk: Develop generalized gradient methods for the minimization.



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Constraint minimization: Conditional gradient method

$$\min_{u \in H} F(u) \text{ subject to } u \in U$$

- 1 Descent direction v^n by

$$\min_{v \in H} \langle F'(u^n), v \rangle \text{ subject to } v \in U$$

- 2 Choose a stepsize $s^n > 0$.
- 3 Update

$$u^{n+1} = u^n + s^n(v^n - u^n)$$

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$$\min_{u \in H} F(u) + I_U(u)$$

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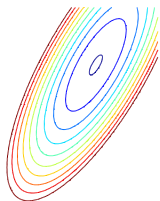
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Generalization of the conditional gradient method

$$\min_{u \in H} F(u) + \Phi(u)$$



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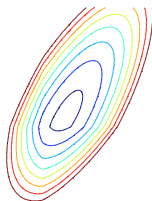
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Convergence Analysis

Condition

- Φ is proper, convex and lsc
- $\partial\Phi$ is onto and $(\partial\Phi)^{-1}$ bounded

Theorem

Let F be Lipschitz and convex, Φ like above. Then the generalized conditional gradient method converges to a minimizer of $F + \Phi$.

(Descent direction is $v^n = (\partial\Phi)^{-1}(-F'(u^n))$.)

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Inverse Problems with sparsity

$$\min_{u \in H} \frac{\|Ku - f\|^2}{2} + \underbrace{\sum_k w_k |u_k|^p}_{\Phi(u)}$$

For $p = 1$:

- Φ is convex and lsc,
- but $\partial\Phi(u) = \sum_k w_k \operatorname{sgn}(u_k)\psi_k$ is not onto.

Workaround 1 \rightsquigarrow soft shrinkage

$$\min_{u \in H} \frac{\|Ku - f\|^2}{2} - \frac{\lambda \|u\|^2}{2} + \underbrace{\frac{\lambda \|u\|^2}{2} + \sum_k w_k |u_k|^p}_{\Phi(u)}$$

$$\partial\Phi(u) = \lambda u + \sum_k w_k \operatorname{sgn}(u_k) \psi_k$$

and hence the descent direction is

$$\begin{aligned} v^n &= (\partial\Phi)^{-1}(\lambda u^n - K^*(Ku^n - f)) \\ &= S_{w/\lambda}(u^n - K^*(Ku^n - f)/\lambda) \end{aligned}$$

(For $\|K\| \leq 1$, $\lambda = 1$ stepsizes $^n = 1$ is ok,
 $\rightsquigarrow u^{n+1} = v^n = S_w(u^n - K^*(Ku^n - f)).$)

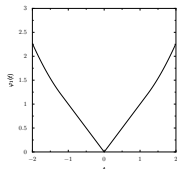
Workaround 2

Estimate the norm of the minimizer u^* :

$$\|u^*\|^p \leq \frac{(F + \Phi)(u^*)}{w_0} \leq \frac{(F + \Phi)(0)}{w_0} = \frac{\|f\|^2}{2w_0}$$

Hence,

$$|u_k| \leq \left(\frac{\|f\|^2}{2w_0} \right)^{1/p} =: S_0.$$



Modify Φ for large values:

$$\tilde{\Phi}(u) = \sum_k w_k \phi(u_k)$$

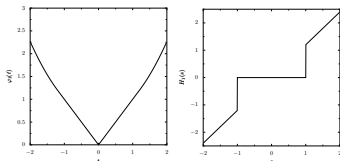
(Quadratic extension in a C^1 way)

Workaround 2 \rightsquigarrow hard shrinkage!

The descent direction is

$$v^n = (\partial\Phi)^{-1}(-K^*(Ku^n - f))$$

$$v_k^n = (\partial\phi)^{-1}(-K^*(Ku^n - f)_k/w_k)$$



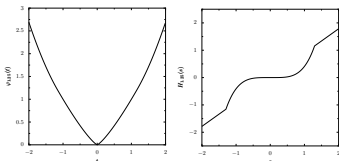
(The special step-size $s^n = \min(1, \frac{\Phi(u^n) - \Phi(v^n) + \langle Ku^n - f, K(u^n - v^n) \rangle}{\|K(v^n - u^n)\|^2})$ guarantees convergence.)

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Properties of the iterated hard shrinkage

Theorem

Let u^* be a minimizer of

$$\Psi(u) = \frac{1}{2} \|Ku - f\|^2 + \sum_k w_k |u_k|^p$$

and u^n, v^n be generated by the iterated hard shrinkage.

- for $1 < p \leq 2$ it holds

$$\|u^n - u^*\| \leq C\lambda^n$$

- for $p = 1$ and K injective it holds

$$\|u^n - u^*\| \leq Cn^{-1/2}.$$

Furthermore the estimate

$D_n = \Phi(u^n) - \Phi(v^n) + \langle K^*(Ku^n - f), u^n - v^n \rangle \geq \tilde{\Psi}(u^n) - \tilde{\Psi}(u^*)$
can serve as a stopping criterion.

Bredies, L. (2006)

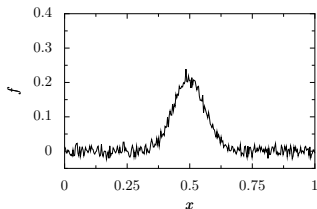
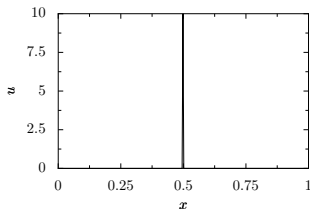


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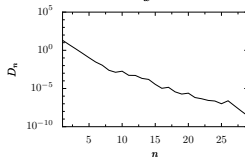
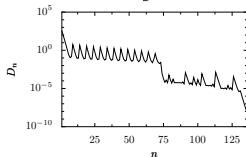
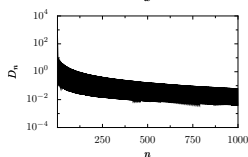
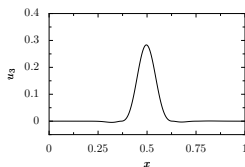
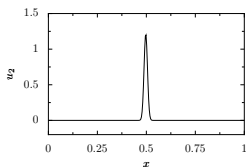
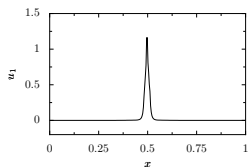
Backwards heat conduction

$$u_t = u_{xx} \text{ for } (t, x) \in [0, T] \times [0, 1]$$
$$u(0, x) = u^0(x)$$
$$u(t, 0) = u(t, 1) = 0.$$

$$Ku^0 = u(T)$$

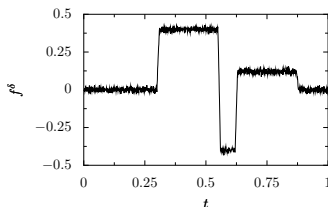
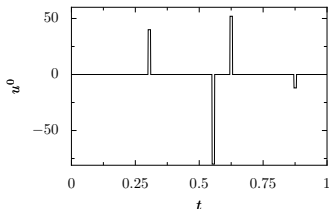


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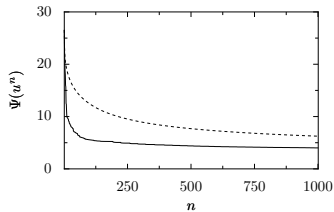
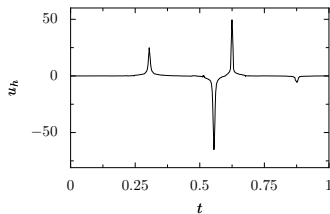
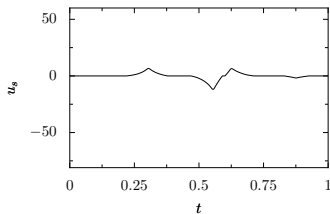


Inverse integration

$$Ku(t) = \int_0^t u(s)ds, \quad s, t \in [0, 1], \quad u \in L^2[0, 1].$$



Inverse integration



Conclusion

- Tikhonov functionals with sparsity constraints can be minimized by **iterated hard shrinkage**.
- The iterated hard shrinkage is **very easy to implement**.
- The convergence speed **changes drastically** from $p > 1$ to $p = 1$.
- The distance to the minimizer can be **estimated easily**.