

Sparse Representations in Power Systems

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Outline

- Background
 - Power Signals
 - Clemson Work
- Theory
- Algorithms
- Operators/Dictionary
- Application
- Conclusions

Signal Properties

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 - Low frequency harmonics - caused by power electronic devices, arc furnaces, transformers, rotational machines, and aggregate loads.
 - Swells and Sags of the RMS Voltage.
 - Transients - caused by lightnings, equipment faults, switching operations, and more.

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 - Capacitor switching transients
 - damped sinusoids with frequency around 1000-2000 Hz
 - damping factor 450-500
 - phase angle $-\pi/2$ to $\pi/2$.

Example Signal with 60Hz Component

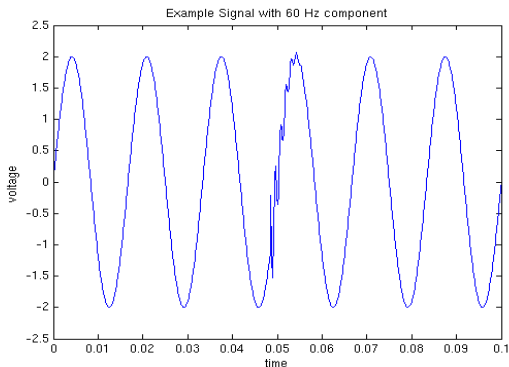


Figure: The test signal with the 60 Hz component, without noise sampled at 1024 points from 0 to .1 seconds.

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- Feature extraction - detect and identify transient disturbance

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NP-Hard, instead

$$\min_{\alpha} \|\alpha\|_1 \text{ subject to } x = \Phi\alpha \quad (2)$$

Or in noise,

$$\min_{\alpha} \lambda \|\alpha\|_1 + \frac{1}{2} \|x - \Phi\alpha\|_2^2 \quad (3)$$

Clemson Research

- Bruckstein, Donoho, Elad - From Sparse Solutions of Systems of Equations to Sparse Modeling of Signals and Images
- Chen, Donoho, Saunders - Atomic Decomposition by Basis Pursuit
- Donoho, Elad - On the Stability of Basis Pursuit in the Presence of Noise
- Donoho, Elad, Temlyakov - Stable Recovery of Sparse Overcomplete Representations in the Precense of Noise
- Tropp - Greed is Good: Algorithmic Results for Sparse Approximation

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- Mutual Coherence analysis

$$\mu(\Phi) = \max_{1 \leq k, j \leq m, k \neq j} \frac{|\phi_k^T \phi_j|}{\|\phi_k\|_2 \|\phi_j\|_2}$$

Used for criteria on finding sparsest solution possible without noise, stability in noise, etc. Often insufficient.

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- Time Frequency Plane Comparison

Lingering Questions

- What about the infinite dimensional setting?
- What other dictionaries might be better?
- What other algorithms are there?

Infinite Dimensional Setting

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- Choose sparse solution from overcomplete basis versus use sparsity constraint as regularization of ill posed problem with injective K
- Difference in how the l^1 penalty function is brought in: regularization compared to the recasting of

$$\min_{\alpha} \|\alpha\|_1 \text{ subject to } \|S - D\alpha\| \leq \delta$$

to

$$\min_{\alpha} \lambda \|\alpha\|_1 + \frac{1}{2} \|x - \Phi\alpha\|_2^2 \quad (4)$$

Regularization

- To what extent is minimizing the functional

$$\Phi(f) = \frac{1}{2} \|Kf - g\|_2^2 + \alpha \|f\|_1 \quad (5)$$

a successful regularization?

Daubechies

Theorem (Daubechies, Defrise, De Mol)

For injective K , a bounded linear operator with $\|K\| < 1$ and $\alpha > 0$, let f^* be the minimizer of Φ . Then for any observed image g , if $\alpha(\epsilon)$ satisfies

$$\lim_{\epsilon \rightarrow 0} \alpha(\epsilon) = 0 \text{ and } \lim_{\epsilon \rightarrow 0} \frac{\epsilon^2}{\alpha(\epsilon)} = 0$$

Then,

$$\lim_{\epsilon \rightarrow 0} \left[\sup_{\|g - Kf_0\| \leq \epsilon} \|f^* - f_0\| \right] = 0$$

where f_0 is the “true” solution.

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This is presented in the literature with a range for p . $p=1$ is used for this context.

Donoho, Elad

Theorem (Donoho, Elad)

With noise level ϵ , a dictionary D of size $N \times L$, and mutual coherence $\mu(D)$, then if the true solution α_0 is sparse enough, satisfying

$$\|\alpha_0\|_0 < \frac{1 + \mu(D)}{2\mu(D) + \sqrt{N}(\epsilon + \delta)/T}$$

then the solution $\hat{\alpha}$ of

$$\min_{\alpha} \|\alpha\|_1 \text{ subject to } \|S - D\alpha\| \leq \delta$$

with $\delta \geq \epsilon$ exhibits stability

$$\|\hat{\alpha} - \alpha_0\|_1 < T.$$

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The dictionary can be overcomplete.

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With noise level ϵ , a dictionary D of size $N \times L$, and mutual coherence $\mu(D)$, then if the true solution α_0 exists with

$$M = \|\alpha_0\|_0 < \frac{\left(\frac{1}{\mu(D)} + 1\right)}{4}$$

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$$\|\hat{\alpha} - \alpha_0\|_2^2 \leq \frac{(\epsilon + \delta)^2}{1 - \mu(D)(4M - 1)}.$$

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Other conditions from Tropp

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$$\Phi_{\alpha}(f) = \|Kf - g\|_2^2 + \alpha\|f\|_1$$

- Minimize this by minimizing a surrogate functional

$$\Phi_{\alpha}^{SUR}(f; a) = \|Kf - g\|_2^2 + \alpha\|f\|_1 - \|Kf - Ka\|_2^2 + \|f - a\|_2^2$$

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- This minimizer satisfies $f = S_{\alpha}(a + [K^*(g - Ka)])$ where

$$S_{\alpha}(x) = \begin{cases} x - \frac{\alpha}{2} & \text{if } x \geq \frac{\alpha}{2} \\ 0 & \text{if } |x| < \frac{\alpha}{2} \\ x + \frac{\alpha}{2} & \text{if } x \leq -\frac{\alpha}{2} \end{cases}$$

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- Iterate using f^{n-1} for a.

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Iterative Soft Thresholding

- When these f^n 's converge to the surrogate minimizer, it also matches the minimizer of Φ !
- if $\|K\| < 1$ and injective then these iterations converge strongly to the minimizer of Φ , regardless of the initial choice.

Iterative Hard Thresholding - Bredies, Lorenz

- Similar to soft thresholding but with a function

$$H(x) = \begin{cases} 0 & \text{for } |x| \leq 1 \\ \frac{\|f\|^2}{2\alpha} & \text{for } |x| > 1 \end{cases}$$

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$$H(x) = \begin{cases} 0 & \text{for } |x| \leq 1 \\ \frac{\|f\|^2}{2\alpha} & \text{for } |x| > 1 \end{cases}$$

- Another function used in the algorithm:

$$\varphi(x) = \begin{cases} |x| & \text{for } |x| \leq \frac{\|f\|^2}{2\alpha} \\ \frac{\alpha}{\|f\|^2} (x^2 + (\frac{\|f\|^2}{2\alpha})^2) & \text{for } |x| > \frac{\|f\|^2}{2\alpha} \end{cases}$$

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- Step Size:

$$s_n = \min \left\{ 1, \frac{\alpha(\varphi(u^n) - \varphi(v^n)) + (K^*(Ku^n - f))(u^n - v^n)}{\|K(v^n - u^n)\|^2} \right\}$$

where the expression makes sense and $s_n = 1$ otherwise.

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- Iterate: $u^{n+1} = u^n + s_n(v^n - u^n)$
- Converges like $n^{-\frac{1}{2}}$ for the l^1 case

Semismooth Newton Method - Griesse, Lorenz

- Solve l^1 penalty minimization by finding the solution to

$$u - S_\alpha(u - \gamma K^*(Ku - f)) = 0$$

where

$$S_\alpha(u_k) = \max\{0, |u_k| - \alpha\} \operatorname{sgn}(u_k)$$

for some $\gamma > 0$.

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 - ④ Initialize Active Sets, set sign vector

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- Active Set Algorithm

- 1 Initialize Active Sets, set sign vector
- 2 Set $u_{I_n}^n = 0$ and calculate $u_{A_n}^n$ by solving

$$K^* K_{A_n, A_n} u_{A_n}^n = (K^* f + (\operatorname{sgn})^n \alpha)_{A_n}$$

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⑤ End if active set does not change, iterate if it does

Semismooth Newton Method

- Converges locally superlinear
- If it converges, then it converges to the global solution

Feature Sign Search - Lee, Battle, Raina, Ng

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then add i to the active set and adjust the sign vector accordingly

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- ④ Feature Sign Step
 - Compute the solution to the unconstrained QP over just the active set, A

$$x_{new} = (A^T A)^{-1} (A^T y - \frac{\alpha \text{sgn}(x)}{2})$$

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Using a line search from x to x_{new} choose the x that minimizes the objective. Update the active set and the sign vector

Feature Sign Search

- Check optimality

For nonzero coefficients: $\frac{\partial \|y - Ax\|^2}{\partial x_i} + \alpha \text{sgn}(x_i) = 0$

If not go back to Step 4 (no new activation)

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- Finds the Global Minimizer
- Considers overcomplete dictionaries

Elastic Net

- Extend the l^1 penalty to include an l^2 regularization also

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- Helps ill-conditioning in Active Set algorithms
- Has unique minimizer even for noninjective K

Basis Learning - Lee, Battle, Raina, Ng

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- Optimize basis vectors for sparse reconstruction by fixing the observed and the input.
- Use a sparse coding algorithm to represent training signals in basis then optimize using Lagrange Dual:

$$\text{trace}(X^T X - X S^T (S S^T + \Lambda)^{-1} (X S^T)^T - c \Lambda)$$

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- Newton search to maximize this dual

Basis Learning - Lee, Battle, Raina, Ng

- Optimize basis vectors for sparse reconstruction by fixing the observed and the input.
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- Iterate this, shrinking B based on zero columns.

Test Signal 1

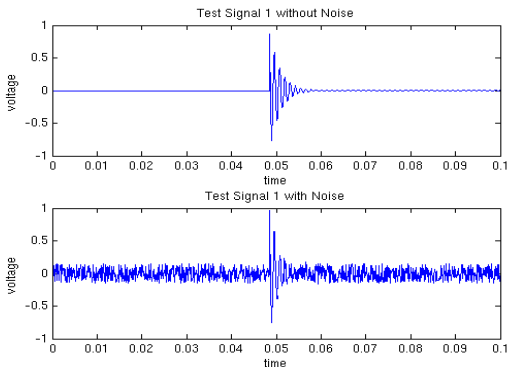


Figure: Test Signal 1 sampled at 1024 points from 0 to .1

Test Signal 2

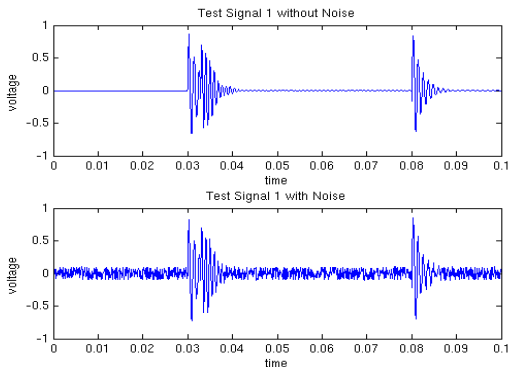


Figure: Test Signal 2 sampled at 1024 points from 0 to .1

How to choose alpha?

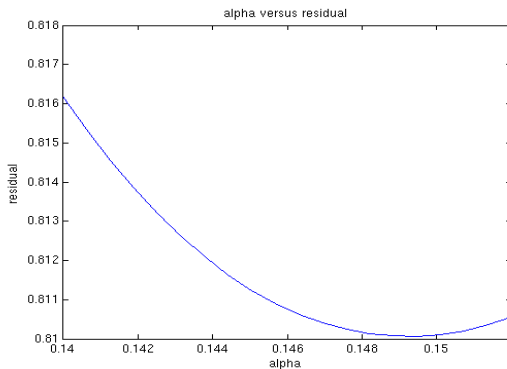


Figure: Alpha values versus the residual of the reconstruction and the noiseless signal. The minimizer is chosen.

Wavelet Dictionary

- Mother wavelet chosen to be Daubechies 4 wavelets

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- Fit well to short impulses
- Level 4 depth
- Previously enumerated all waveforms of a wavelet packet - prohibitively big, now can use function handle

Wavelet Dictionary Results

- The optimal alpha value is selected at .1467
- The number of nonzeros is 113.

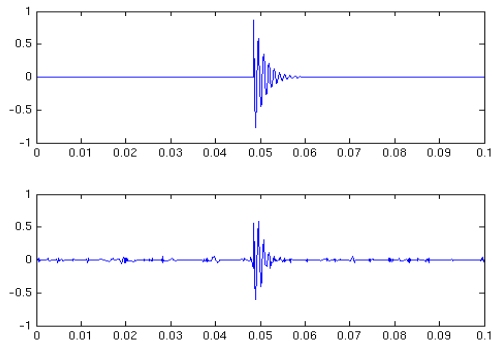


Figure: The reconstruction compared to the noiseless signal

Wavelet Dictionary Results

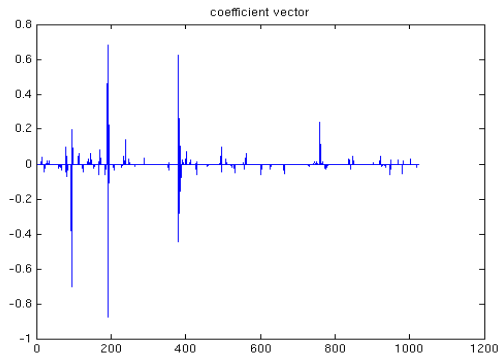


Figure: The coefficient vector

Wavelet Dictionary Results

Algorithm	Runtime (s)
Soft Thresholding	0.022067
Hard Thresholding	max Iter
SSN	∞
FSS	0.690612
Elastic Net SSN	0.370986
Elastic Net FSS	0.729112
GPSR	0.099766
Interior Point	15.021680

Table: Algorithm running times on Wavelet Operator, Test Signal 1

Wavelet Dictionary Results Signal 2

- The optimal alpha value is selected at .0747
- The number of nonzeros is 291

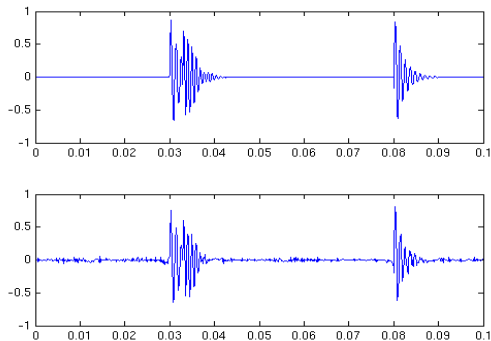


Figure: The reconstruction compared to the noiseless signal

Wavelet Dictionary Results Signal 2

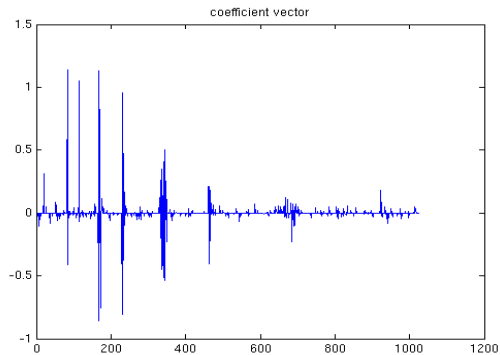


Figure: The coefficient vector

Wavelet Dictionary Results Signal 2

Algorithm	Runtime (s)
Soft Thresholding	0.021567
Hard Thresholding	max Iter
SSN	∞
FSS	2.305259
Elastic Net SSN	0.392921
Elastic Net FSS	2.449922
GPSR	0.162870
Interior Point	14.193927

Table: Algorithm running times on Wavelet Operator, Test Signal 2

Learned Dictionary

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- Frequencies, damping factors over range associated with capacitor switches
- Starting points range over 0 to .1
- Sized pared down to 354 from learning, much easier to deal with

Learned Dictionary Results

- The optimal alpha is .0495.
- The number of nonzeros is 13.

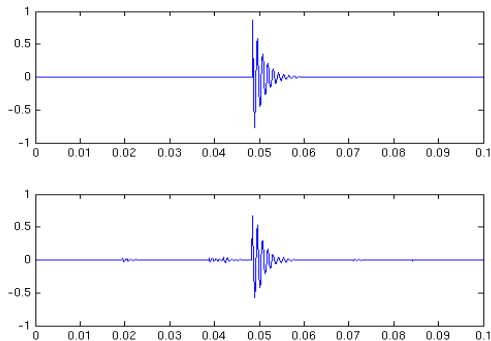


Figure: The reconstruction compared to the noiseless signal

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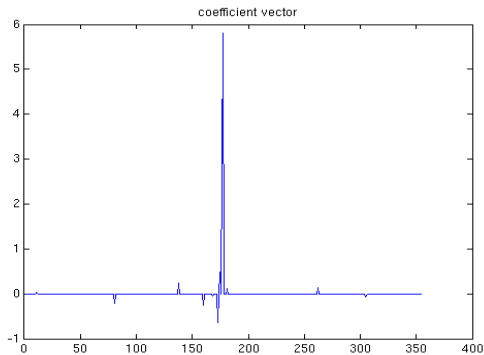


Figure: The coefficient vector

Learned Dictionary Results

Algorithm	Runtime (s)
Soft Thresholding	0.633864
Hard Thresholding	max iter
SSN	∞
FSS	0.078537
Elastic Net SSN	0.089418
Elastic Net FSS	0.078365
GPSR	0.099766
Interior Point	7.790935

Table: Algorithm running times on Learned Basis Dictionary, Test Signal 1

Learned Dictionary Results Signal 2

- The optimal alpha is $\alpha=5.6000e-06$
- The number of nonzeros is 249.

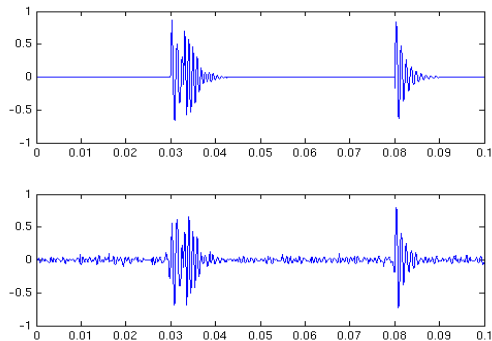


Figure: The reconstruction compared to the noiseless signal

Learned Dictionary Results Signal 2

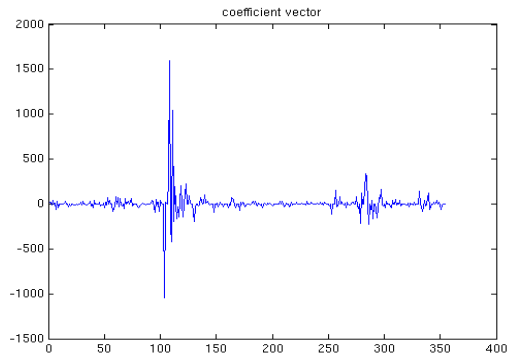


Figure: The coefficient vector

Learned Dictionary Results Signal 2

Algorithm	Runtime (s)
Soft Thresholding	max Iter
Hard Thresholding	max Iter
SSN	∞
FSS	7.975966
Elastic Net SSN	0.348048
Elastic Net FSS	5.441613
GPSR	max Iter
Interior Point	73.504971

Table: Algorithm running times on Learned B, Test Signal 2

This time the elastic net beta parameter had an effect resulting a solution of 322 nonzeros, but improved running time. beta taken as $1e-6$.

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- How to find the best alpha value? How to find the best alpha and beta in Elastic Net?
- Elastic Net helps SSN converge on a solution - particularly in the messy last case
- The learned dictionary is very sparse when close to the training signals, not so much otherwise

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- How would OMP perform in this case?
- How to classify detected transients?

Solver Developers

- Iterative Thresholding Methods - Dirk Lorenz
- FSS - Stefan Schiffler
- SNN - Stefan Schiffler
- Basis Learning - Klaus Steinhorst
- GPSR - Mario Figueiredo, Robert Nowak, Stephen Wright
- Interior Point Method - SparseLab
- Wavelet Operator - Sparco

Thanks

Thanks to those who wrote the code I plundered, to Stefan for helping, and to the audience for listening.